

# Hamiltonian singularities in the STIRAP process

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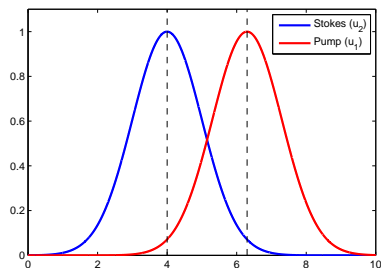
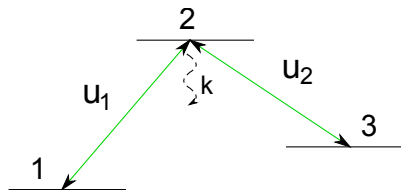
# Outline

About STIRAP

Hamiltonian Singularities

Optimal control

# Stimulated Raman Adiabatic Passage



- A counterintuitive sequence.
- Avoids dissipation of state  $|2\rangle$ .

## About STIRAP

- Dynamics :

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{pmatrix} = \begin{pmatrix} -u_1 x_2 \\ u_1 x_1 - k x_2 + u_2 x_3 \\ -u_2 x_3 \end{pmatrix}$$

- Dark state :

$$|\psi\rangle = \begin{pmatrix} \cos \phi \\ 0 \\ -e^{i\Phi_r} \sin \phi \end{pmatrix} \quad \text{with} \quad \tan \phi = \frac{u_1}{u_2}, \quad \Phi_r = \Phi_1 - \Phi_2$$

- An adiabatic process  $\rightarrow$  infinitely long dynamics.
- A robust process.
- Optimal ? for which cost ?

# Integrable hamiltonian systems

- $K$  is a constant of motion  $\Leftrightarrow \frac{dK}{dt} = 0$ .
- **Integrable**  $\Leftrightarrow$  As many constants of motion as degrees of freedom.
- Action-Angle variables :  $(p_k, q_k) \rightarrow (I_k, \theta_k)$

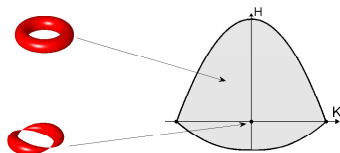
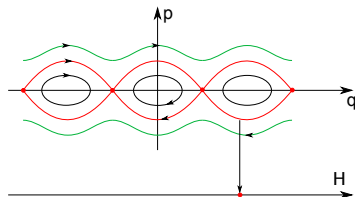
$$\left\{ \begin{array}{l} \dot{q} = \frac{\partial H}{\partial p} \\ \dot{p} = -\frac{\partial H}{\partial q} \end{array} \right. \longrightarrow \left\{ \begin{array}{l} \dot{\theta}_k = \omega(I_k) \\ \dot{I}_k = 0 \end{array} \right.$$

- Arnold-Liouville Theorem : Action-Angle variables exist locally.
- $I_k$  constants  $\Leftrightarrow$  a **torus** in the phase space.

# Singular Tori

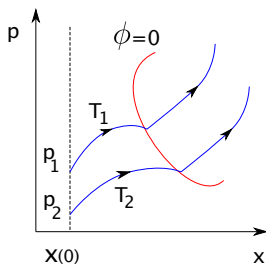


# Energy-Momentum Diagram



- $(H, K)$  space  $\Leftrightarrow$  Energy-Momentum diagram.
- One value of  $(H, K)$   $\Leftrightarrow$  One torus in the phase space
- Singular tori  $\Leftrightarrow$  Trajectories with infinite periods.

# Pontryagin Maximum Principle



Dynamical system with a cost :

- $\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x}, u), \quad C = \int_0^T f_0(\mathbf{x}, u)$

Pseudo-Hamiltonian with co-state  $p$  :

- $\mathcal{H} = \mathbf{p} \cdot \mathbf{f}(\mathbf{x}, u) + p_0 f_0(\mathbf{x}, u)$

Maximization condition :

- $H = \max_{u \in U} \mathcal{H}(\mathbf{x}, \mathbf{p}, u)$

Hamiltonian dynamical system :

- $$\begin{aligned} \dot{\mathbf{x}} &= \frac{\partial \mathcal{H}}{\partial \mathbf{p}} \\ \dot{\mathbf{p}} &= -\frac{\partial \mathcal{H}}{\partial \mathbf{x}} \end{aligned}$$



## Energy minimum cost

- Cost :

$$C = \int_0^T [u_1^2(t) + u_2^2(t)] dt$$

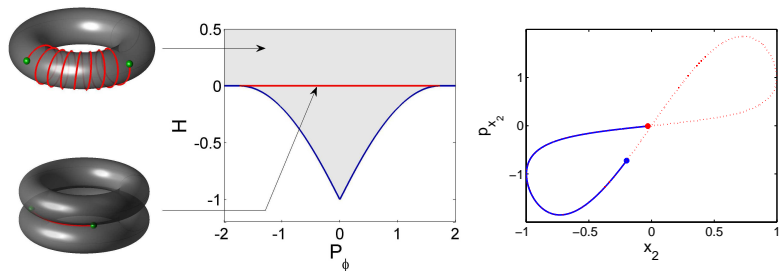
- Pseudo Hamiltonian :

$$H = -krp_r \cos^2 \theta + k \cos \theta \sin \theta p_\theta + \frac{1}{2} p_\theta^2 + \frac{1}{2} \cot^2 \theta p_\phi^2$$

with :

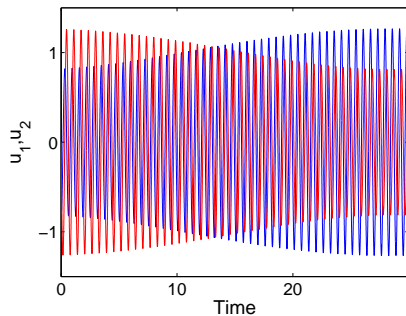
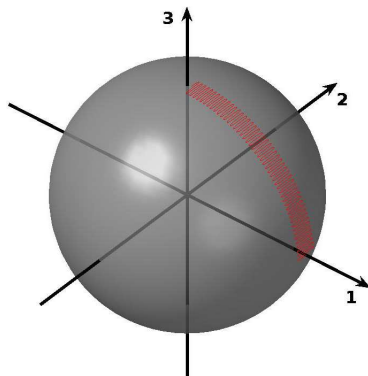
$$\begin{cases} x_1 = r \sin \theta \cos \phi \\ x_2 = r \cos \theta \\ x_3 = r \sin \theta \sin \phi \end{cases}$$

# Phase space structure



- STIRAP would be on a bitorus.
- Not allowed by the dynamics.

## Example of energy minimum controls



- Far from a STIRAP process.
- Avoids most of dissipation of state  $|2\rangle$ .

## Stirap cost

- Cost :

$$C = \int_0^T \dot{\theta}^2$$

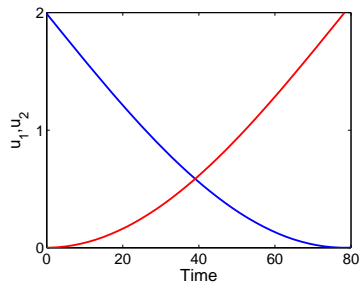
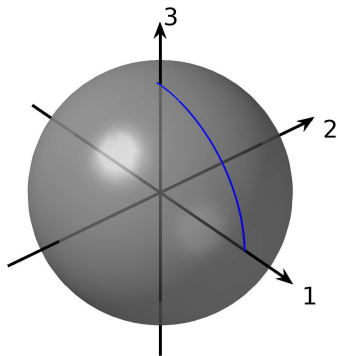
- Maximized Hamiltonian :

$$H = -krp_r \cos^2 \theta + \frac{1}{2}p_\theta^2 - v_2 \cot \theta p_\phi$$

where

$$v_2 = -\frac{2krp_r \sin^3 \theta \cos \theta}{p_\phi} \quad \text{and} \quad \theta = \frac{\pi}{2} + \epsilon$$

## Example of STIRAP-like trajectory



- Counterintuitive sequence
- $\lim_{\theta \rightarrow \frac{\pi}{2}} : \tan \phi = \frac{u_1}{u_2}$

# Summary

- STIRAP-like trajectories can be obtained with the PMP.
- It minimizes oscillations around the dark state.
- It corresponds to a singular torus of the integrable Hamiltonian system.

## Perspectives

- Link between robustness and singular torus ?
- The space structure depends on the cost ?